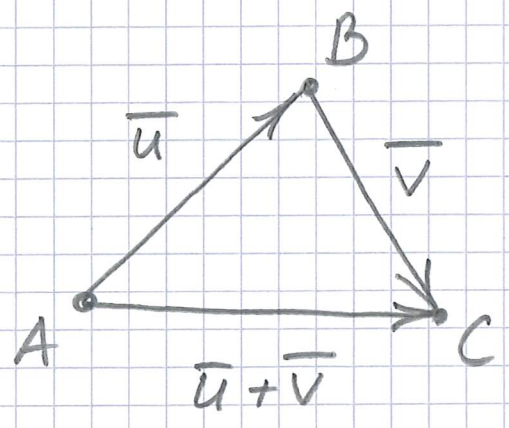
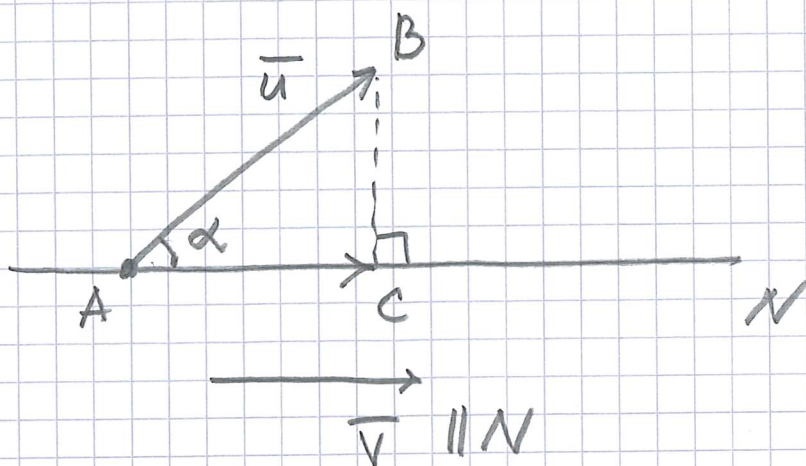


$$\vec{u} \cdot \vec{v} = |\vec{u}| \cdot |\vec{v}| \cdot \cos \alpha$$



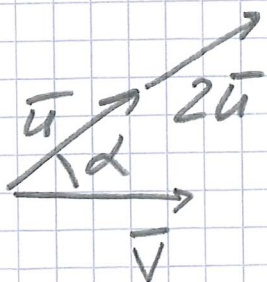
$$|\vec{u} + \vec{v}| \leq |\vec{u}| + |\vec{v}|$$



$$\begin{aligned} \cdot \quad \text{pr}_N \vec{u} &= \frac{\vec{u} \cdot \vec{v}}{|\vec{v}|^2} \cdot \vec{v} \\ \parallel & \\ \vec{AC} &= |\vec{AC}| \cdot \left( \frac{1}{|\vec{v}|} \cdot \vec{v} \right) = \text{←} \text{ einheitsvektor} \\ &= \frac{|\vec{AB}| \cdot \cos \alpha \cdot |\vec{v}|}{|\vec{v}|} \cdot \frac{1}{|\vec{v}|} \cdot \vec{v} = \\ &= \frac{\vec{u} \cdot \vec{v}}{|\vec{v}|^2} \cdot \vec{v} \quad \underline{v \cdot v} \end{aligned}$$

$$\begin{aligned} \cdot \quad \vec{u} \cdot \vec{v} &= \text{pr}_N \vec{u} \cdot \vec{v} \\ \parallel & \\ \underline{|\vec{u}| \cdot \cos \alpha \cdot |\vec{v}|} &= |\text{pr}_N \vec{u}| \cdot |\vec{v}| \cdot 1 = \\ &= \text{pr}_N \vec{u} \cdot \vec{v} \end{aligned}$$

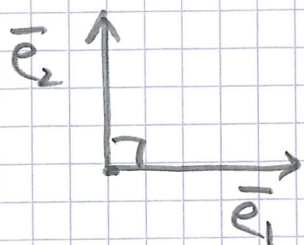
$$(2 \cdot \vec{u}) \cdot \vec{v} = 2 \cdot (\vec{u} \cdot \vec{v})$$



$$\begin{aligned} \text{v.l.} &= |2 \cdot \vec{u}| \cdot |\vec{v}| \cdot \cos \alpha = 2 |\vec{u}| \cdot |\vec{v}| \cdot \cos \alpha \\ &= 2 \cdot (\vec{u} \cdot \vec{v}) = \text{H.L.} \end{aligned}$$

Satz Om  $\vec{u} = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix}$ ,  $\vec{v} = \begin{pmatrix} x_2 \\ y_2 \end{pmatrix}$   
 in ON bas  $\vec{e}_1, \vec{e}_2$  Si  $\vec{u}$

$$\boxed{\vec{u} \cdot \vec{v} = x_1 \cdot x_2 + y_1 \cdot y_2}$$



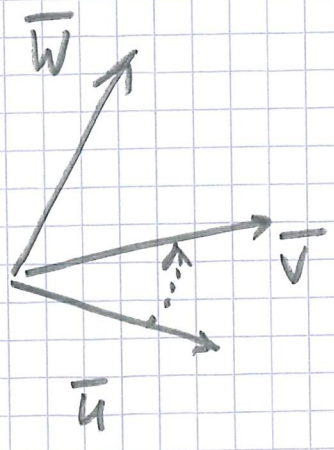
$$\vec{e}_1 \cdot \vec{e}_1 = |\vec{e}_1| \cdot |\vec{e}_1| = 1$$

$$\vec{e}_1 \cdot \vec{e}_2 = |\vec{e}_1| \cdot |\vec{e}_2| \cdot 0 = 0$$

$$\vec{e}_2 \cdot \vec{e}_2 = 1$$

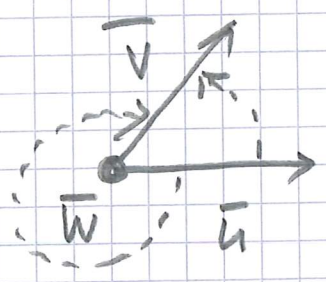
Obs  $|\vec{u}| = \sqrt{\vec{u} \cdot \vec{u}} = \sqrt{x_1^2 + y_1^2}$

EH högersystem



(u, v, w) Obs ordning!

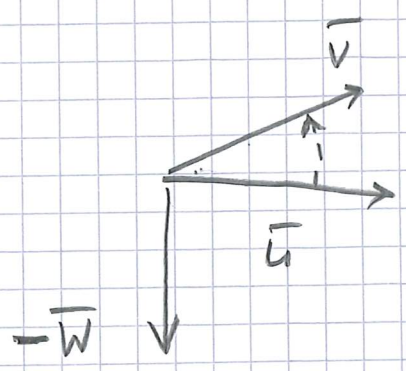
Syn från spetsen av  $\bar{w}$   
på planet där  $\bar{u}, \bar{v}$  ligger:



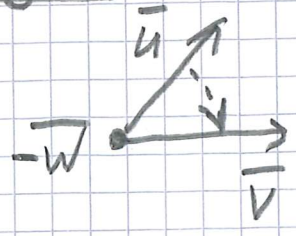
den minsta vridning  
som överför  $\bar{u}$  till  $\bar{v}$ 's  
position ses moturs

EH vänstersystem

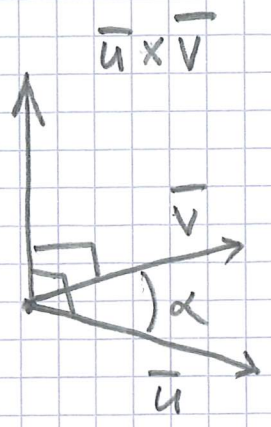
(u, v, -w)



Syn ...

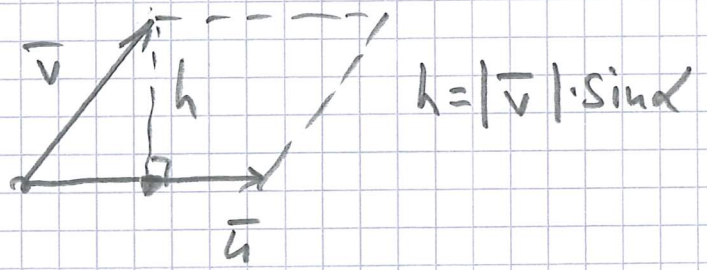


# Vektorprodukt



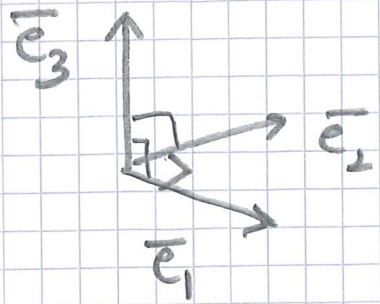
definieras av:

- $\vec{u} \times \vec{v} \perp \vec{u}, \vec{v}$
- $(\vec{u}, \vec{v}, \vec{u} \times \vec{v})$  är ett högersystem
- $|\vec{u} \times \vec{v}| = |\vec{u}| \cdot |\vec{v}| \cdot \sin \alpha$   
//  
Area av



(6)

Ex: Anta att



$(\bar{e}_1, \bar{e}_2, \bar{e}_3)$  är ett höger sys.

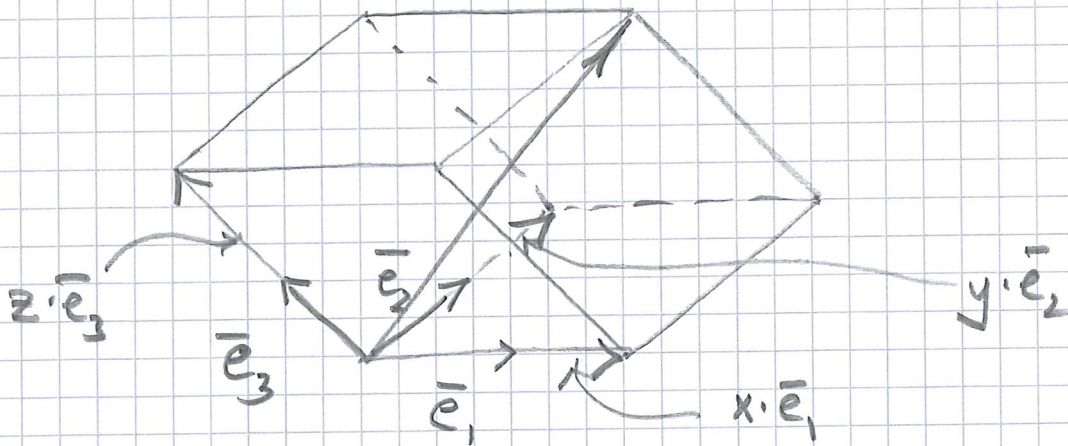
$|\bar{e}_i| = 1$  o  $\bar{e}_i \perp \bar{e}_j$   
för  $i \neq j$

$$\Rightarrow \bar{e}_1 \times \bar{e}_2 = \bar{e}_3$$

$$\bar{e}_1 \times \bar{e}_1 = \vec{0} \quad \text{o s v}$$

$$\bar{e}_1 \times \bar{e}_3 = -\bar{e}_2$$

$\mathcal{E}_n$  bas i rummet:



$$\vec{w} = x \cdot \bar{e}_1 + y \cdot \bar{e}_2 + z \cdot \bar{e}_3$$

$$\vec{w} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

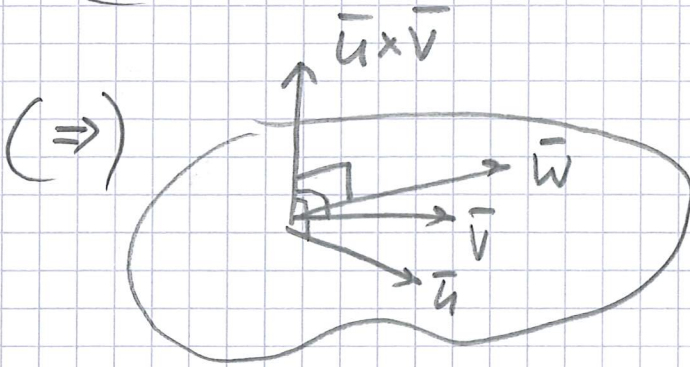
om  $\bar{e}_1, \bar{e}_2, \bar{e}_3$  är fixerad

# Trippelprodukt

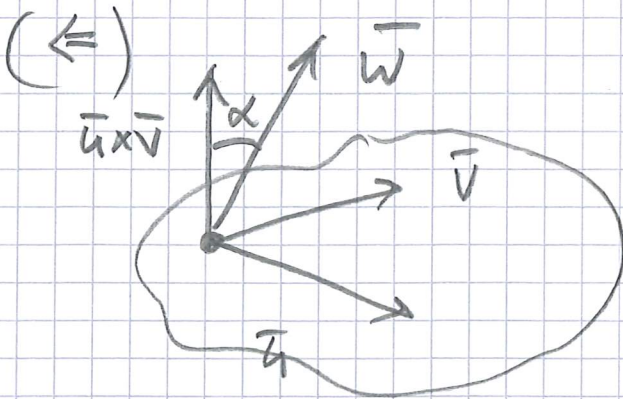
$$(\bar{u}, \bar{v}, \bar{w}) = (\bar{u} \times \bar{v}) \cdot \bar{w} \quad (\text{def.})$$

$\bar{u}, \bar{v}, \bar{w}$  "ligger" i samma plan  $\Leftrightarrow$

$$(\bar{u} \times \bar{v}) \cdot \bar{w} = 0$$



$$\Rightarrow (\bar{u} \times \bar{v}) \cdot \bar{w} = |\bar{u} \times \bar{v}| \cdot |\bar{w}| \cos \frac{\pi}{2} = 0$$



$$\begin{aligned}
 (\bar{u} \times \bar{v}) \cdot \bar{w} &= \\
 &= |\bar{u} \times \bar{v}| \cdot |\bar{w}| \cdot \cos \alpha \\
 &\quad \neq 0 \quad \neq 0 \quad \neq 0 \\
 &\neq 0
 \end{aligned}$$