

① Euklidische v.v., rep.

V v.v.

$(\cdot | \cdot)$ inner prod

$$1) (\bar{u}_1 + \bar{u}_2 | \bar{v}) = (\bar{u}_1 | \bar{v}) + (\bar{u}_2 | \bar{v})$$

$$2) (c\bar{u} | \bar{v}) = c(\bar{u} | \bar{v})$$

$$3) (\bar{u} | \bar{v}) = (\bar{v} | \bar{u})$$

$$4) (\bar{u} | \bar{u}) \geq 0$$

und gleich 0 genau, $\bar{u} = \bar{0}$

$$\text{Inkr: } \|\bar{u}\| = \sqrt{(\bar{u} | \bar{u})}$$

$$d(\bar{u}, \bar{v}) = \|\bar{u} - \bar{v}\| \\ = \|\bar{v} - \bar{u}\|$$

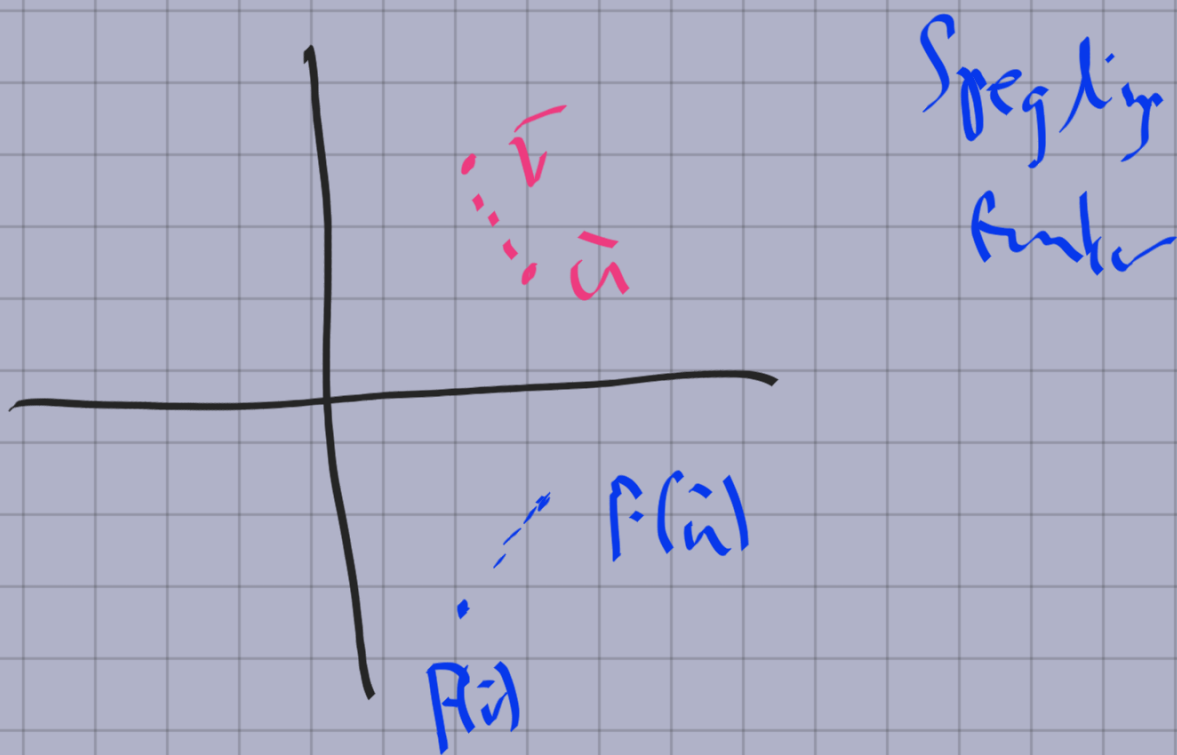
$$\bar{u} \perp \bar{v} \quad \text{omn} \quad (\bar{u} | \bar{v}) = 0$$

V Euklidisk,

$F: V \rightarrow V$ linj. avl

Def F isometrisk om

$$d(F(\bar{u}), F(\bar{v})) = d(\bar{u}, \bar{v}) \\ \text{allt } \bar{u}, \bar{v} \in V$$



Satz Folgende gelten:

- 1) F isb
- 2) $\|F(\vec{u})\| = \|\vec{u}\| \quad \text{all } \vec{u}$
- 3) $(F(\vec{u}) | F(\vec{v})) = (\vec{u} | \vec{v})$
all \vec{u}, \vec{v}

B) 1) \Rightarrow 2):

$$\|F(\bar{u})\| = d(F(\bar{u}), \bar{o})$$

erl 1)

$$= d(\bar{u}, \bar{o}) = \|\bar{u}\|$$

2) \Rightarrow 3):

$$\|F(\bar{u}) + F(\bar{v})\|^2 = \|F(\bar{u} + \bar{v})\|^2$$

2)

$$= \|\bar{u} + \bar{v}\|^2$$

$$VL = (F(\bar{u}) + F(\bar{v}) | F(\bar{u}) + F(\bar{v}))$$

$$= \|F(\bar{u})\|^2 + \|F(\bar{v})\|^2 + 2(F(\bar{u}) | F(\bar{v}))$$

$$\| \bar{u} + \bar{v} \|^2 = \|\bar{u}\|^2 + \|\bar{v}\|^2 + 2(\bar{u} | \bar{v})$$

$$\text{si } 2(\bar{u} | \bar{v}) = 2(\bar{u} | \bar{v})$$

$$3) \Rightarrow 1) \quad d(F(\bar{u}), F(\bar{v}))^2$$

$$= (F(\bar{u}) - F(\bar{v}) | F(\bar{u}) - F(\bar{v}))$$

$$= (F(\bar{u} - \bar{v}) | F(\bar{u} - \bar{v}))$$

$$\stackrel{\text{red}}{=} (\bar{u} - \bar{v} | \bar{u} - \bar{v})$$

$$= d(\bar{u}, \bar{v})^2$$

Satz O_m $\underline{e} = (\bar{e}_1, \dots, \bar{e}_n)$ ONB

für V , $F(\underline{e}X) = \underline{e}AX$

Sk $A^t A = I$,

Orthonormal, $\underline{e}X \mapsto \underline{e}AX$

wel $A^t A = I$ ist iso.

$$\boxed{B} \quad (\underline{e}X | \underline{e}Y) = X^t Y$$

$$= (\underline{e}AX | \underline{e}AY) =$$

$$= (AX)^t (AY) = X^t A^t AY$$

För alla X, Y så

$$X^t I Y = X^t (A^t A) Y$$

$$\text{så } I = A^t A$$

Lemma $A^t A = I$

$$\text{om } A^{-1} = A^t$$

om kol i A bildar ON-bas

om rad i A bildar ON-bas

$$\text{Ex } A = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$A^t A = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = 0$$

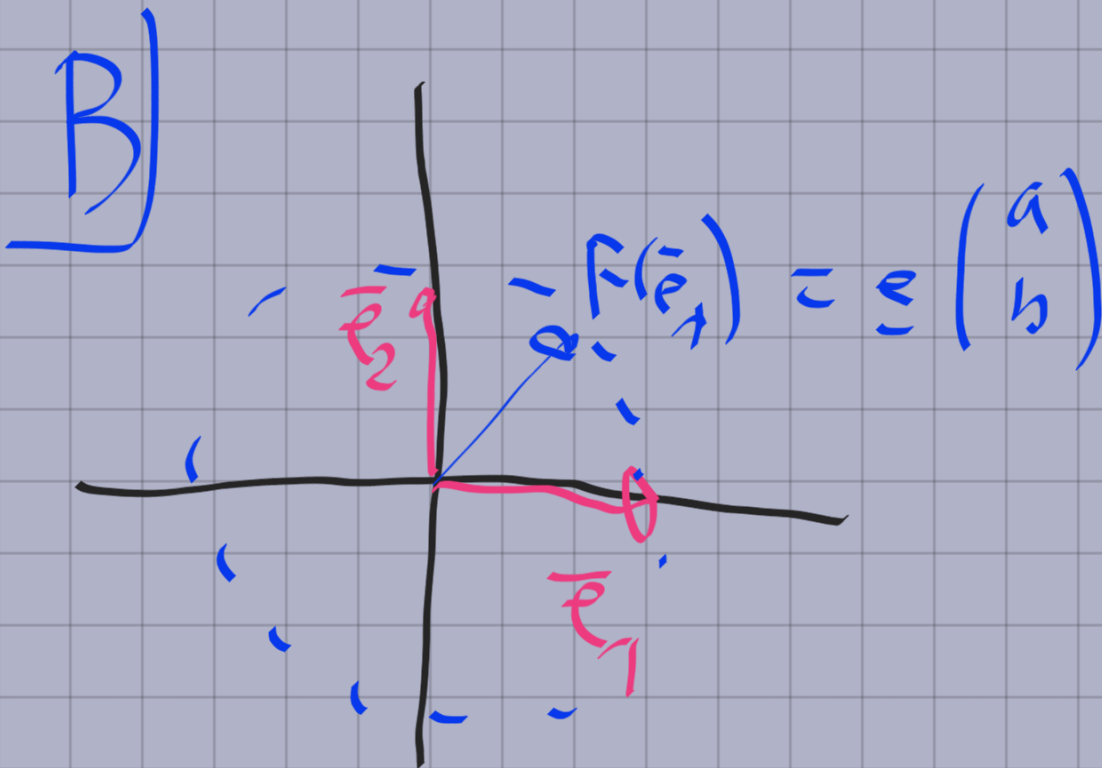
\swarrow
 vektor; A^t
 kol 1; A

kol 2; A

$A_1 \perp A_2$

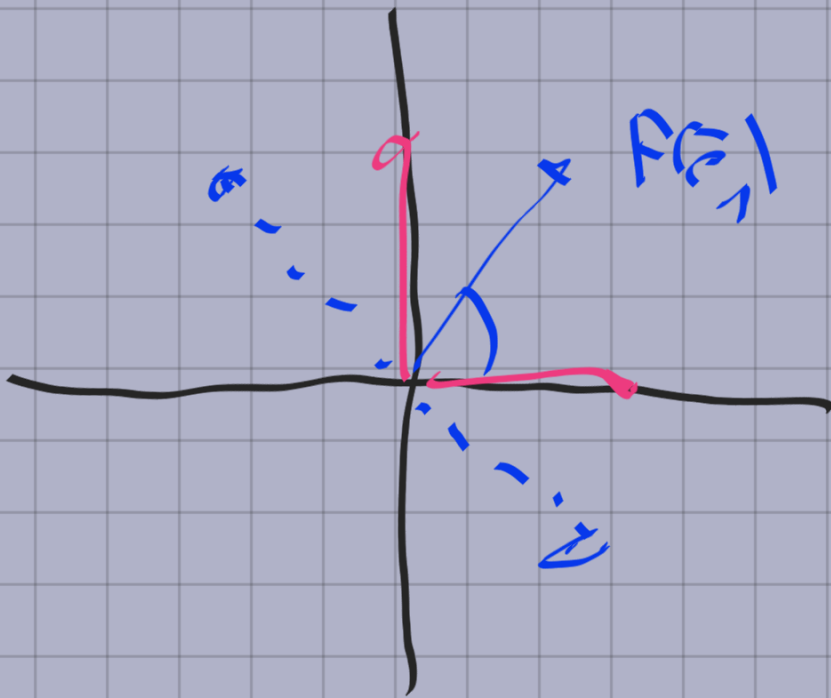
Sats Isometrier

i planet är vridningar
el speglingar.



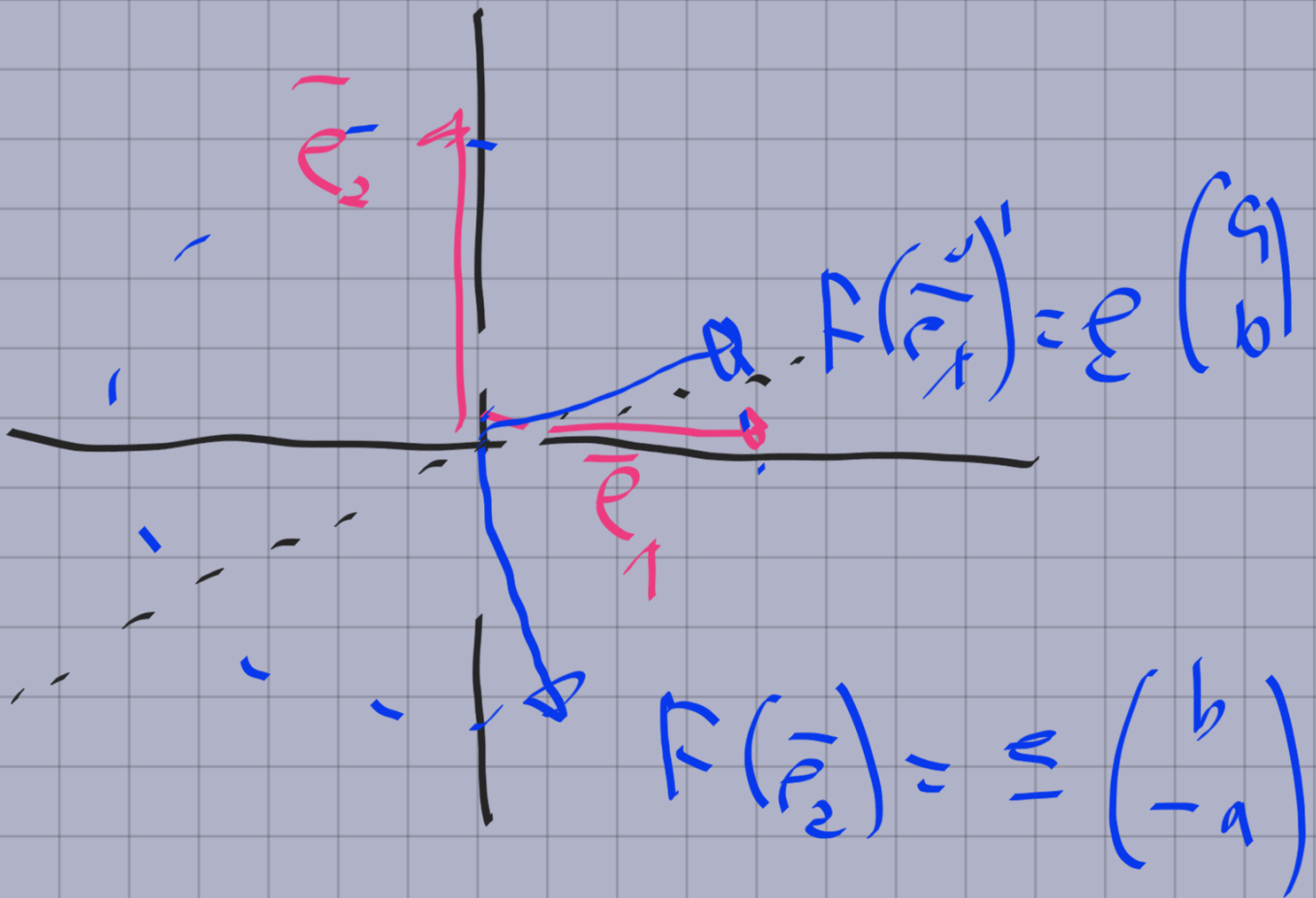
$$F(\vec{e}_2) \perp F(\vec{e}_1) \quad \text{så}$$

$$F(\hat{e}_2) = \pm e \begin{pmatrix} -b \\ a \end{pmatrix}$$



Fall 1: unidring (und α rad,
 $\cos(\alpha) = a$
 $\sin(\alpha) = b$)

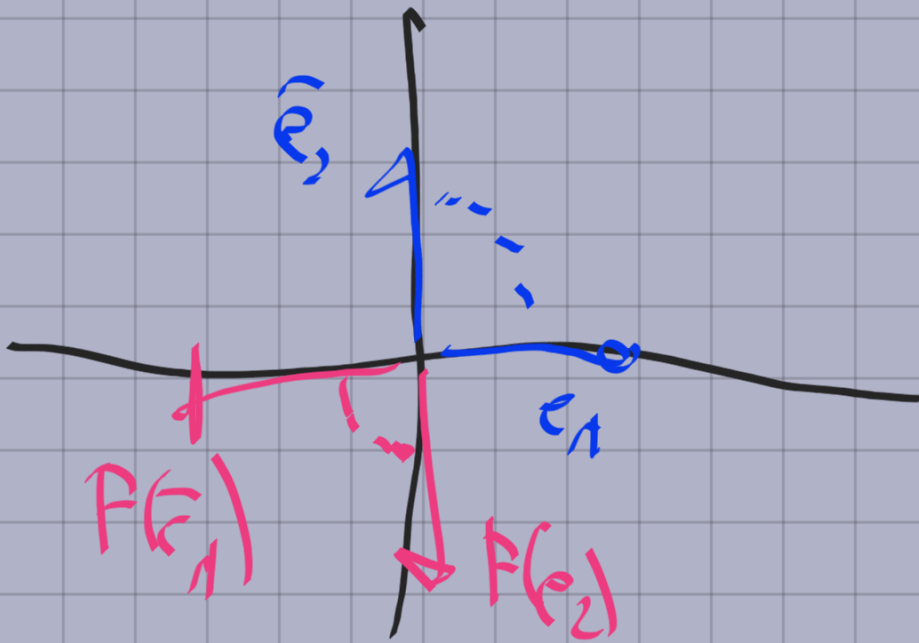
Fall 2: Sprengling!



$$\lambda = \left[\frac{1}{2} \vec{e}_1 + \frac{1}{2} F(\vec{e}_1) \right]$$

$$\underline{E}_x \quad A = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$$

kol ON, si ISO.
 V_{ed}^2 ,



$F(\cdot)$ "Roe", si unidirec.

180°

Satz 1.50 i rummet

är

1) Vridning (vinkel)

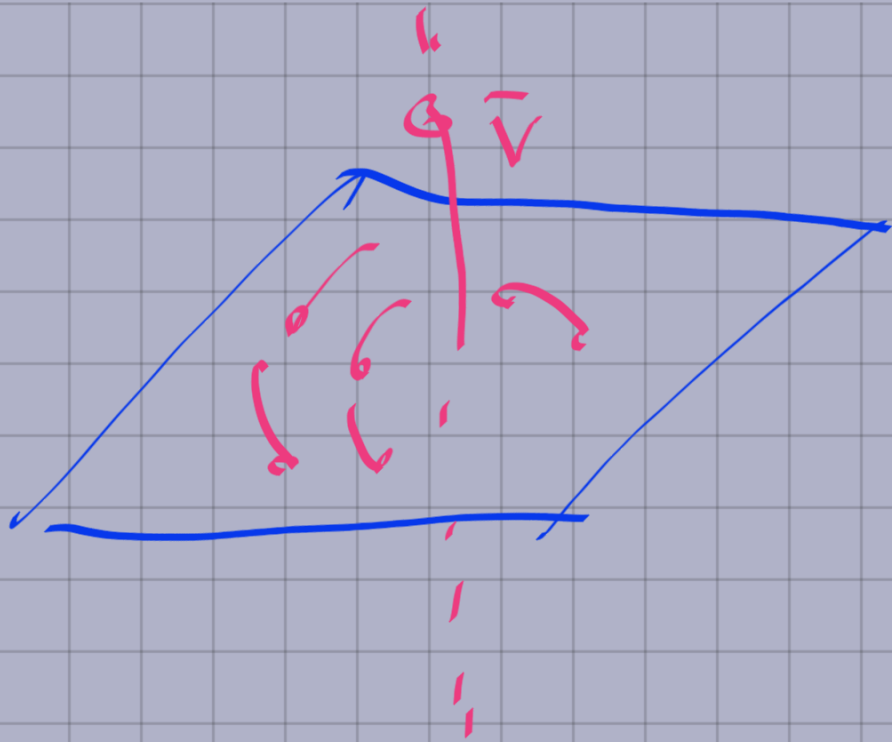
2) Spiegling (i plan)

eller

3) Vridspiegling (kombination)

B) Kvadrater!

1)



$$F(\vec{v}) = \vec{v}$$

$$F(\text{plane}) = \text{plane}$$

2)



$$F(\vec{v}) = -\vec{v}$$

$$F(\vec{u}) = \vec{u}$$

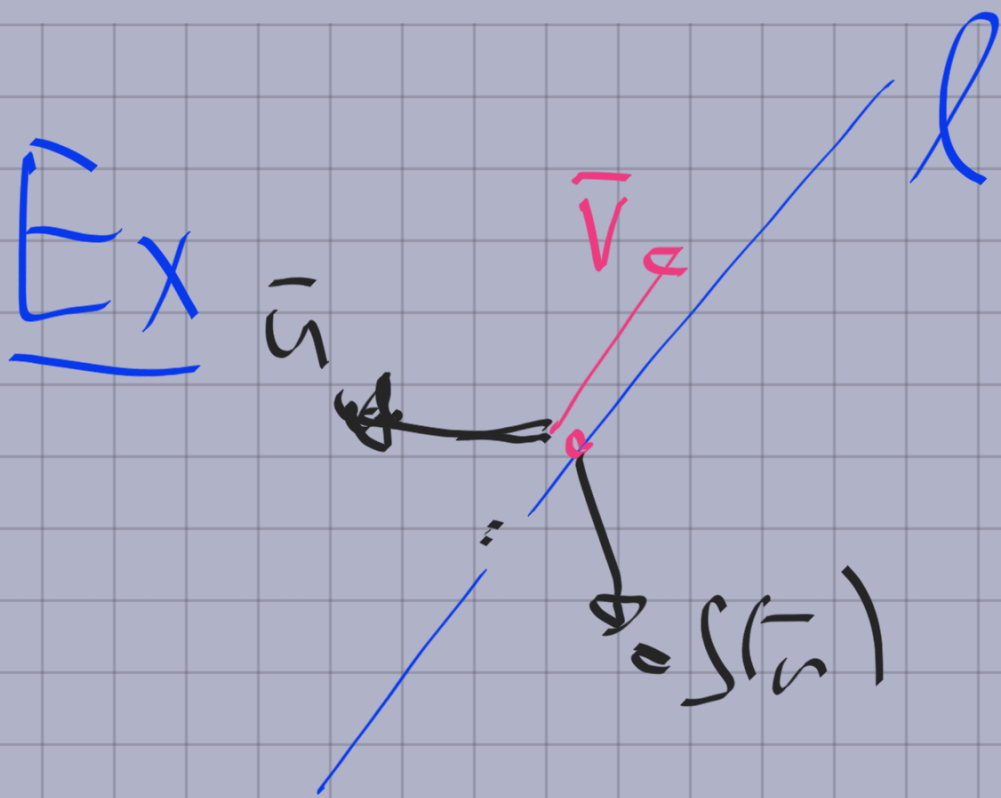
alle $\vec{v} \in \text{plane}$

3)



$$F(\vec{v}) = -\vec{v}$$

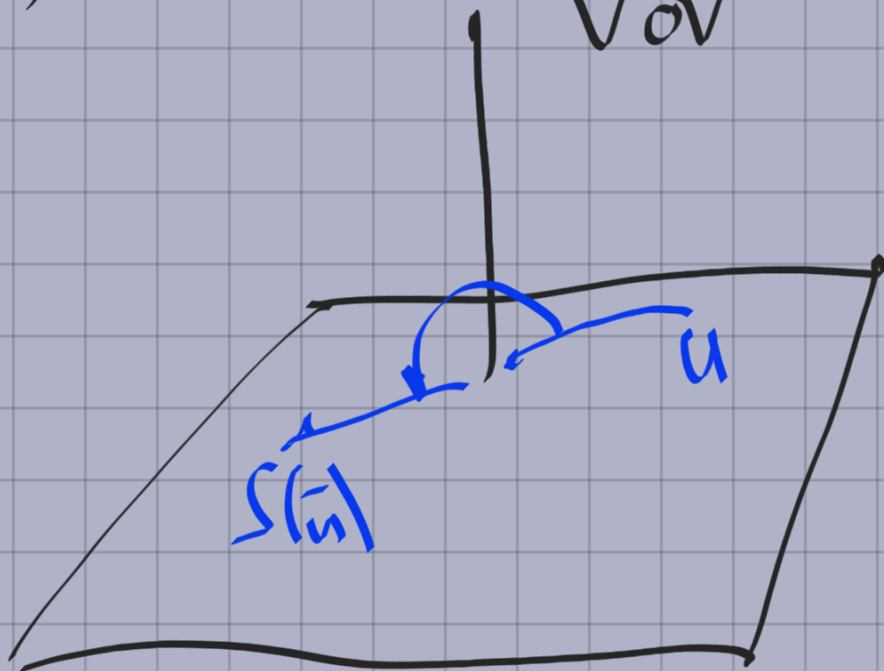
$$F(\text{plane}) = \text{plane}$$



Spiegelung i linje, i rummet.

$$S(\vec{u}) = \vec{u} - 2 \frac{\vec{u} \cdot \vec{v}}{\vec{v} \cdot \vec{v}} \vec{v}$$

Mer:



Vinkel 180° runt \vec{v}

Satz $F: V \rightarrow V$ linj,

$$F(\underline{e}_X) = \underline{e} A X$$

$$F(\underline{f}_Y) = \underline{f} B Y$$

$$\text{Def: } \det(A) = \det B \\ (= \det F).$$

Visus nisk horelörning:

Satz F isd $\Rightarrow \det F \in \{-1, 1\}$

i punkt: +1 undring, -1 spegling

i rummet: +1 undring

-1 spegl el und spegl.

$$B) \quad A^t A = I$$

$$\implies \det(A^t A) = \det(I) = 1$$

$$\text{wenn } \det(A^t A) = \det(A^t) \det(A) \\ = \det(A)^2$$

$$\text{Somit } \det(A)^2 = 1.$$

$$\bullet \begin{vmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{vmatrix} = \cos^2 \alpha + \sin^2 \alpha = 1$$

$$\bullet \begin{vmatrix} 1 & 0 \\ 0 & -1 \end{vmatrix} = -1$$



Linjära isometrier

Avståndsbevarande,
normbevarande,
inreprodukt-bevarande

ON-matriser

Determinant av isometri

Isometrier i planet

Isometrier i rummet

Symmetriska linjära
avbildningar

Exempel

Vad är det för avbildning som (map någon ON-bas) har avbildningsmatris

$$M = \frac{1}{3} \begin{pmatrix} 1 & 2 & -2 \\ 2 & -2 & -1 \\ 2 & 1 & 2 \end{pmatrix} ?$$

❶ $M^t M = I$, så isometri

❷ $\det(M) = -1$ så vridspegling eller spegling

❸ $MX = -X$ kan skrivas $(M + I)X = 0$, nollrum till $\frac{1}{3} \begin{pmatrix} 4 & 2 & -2 \\ 2 & 1 & -1 \\ 2 & 1 & 5 \end{pmatrix}$ är span $\left(\begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} \right)$

❹ Så linjen ℓ är span $\left(\begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} \right)$ och planet Π är $x - 2y = 0$.



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Exempel (forts)

5 Ta vektor av längd ett i planet, tex $\bar{u} = \underline{e} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

6 $F(\bar{u}) = \underline{e} M \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \underline{e} \begin{bmatrix} -2/3 \\ -1/3 \\ 2/3 \end{bmatrix} = \bar{v}$ har också längd ett, så vi mäter vinkeln mellan \bar{u} och \bar{v} genom $\cos(\alpha) = \bar{u} \cdot \bar{v} = 2/3$

7 Så avbildningen är en vridning med $\arccos(2/3)$ runt ℓ , följt av en spegling i Π .

8

$$\bar{u} \times F(\bar{u}) = \underline{e} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \times \underline{e} \begin{bmatrix} -2/3 \\ -1/3 \\ 2/3 \end{bmatrix} = \underline{e} \begin{bmatrix} 1/3 \\ -2/3 \\ 0 \end{bmatrix}$$

så vridningen sker *moturs* sett från spetsen av $\begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix}$

$$(\bar{u} \times F(\bar{u})) = +\frac{1}{3} \bar{n}$$



Linjära isometrier

Avståndsbevarande,
normbevarande,
inreprodukt-bevarande

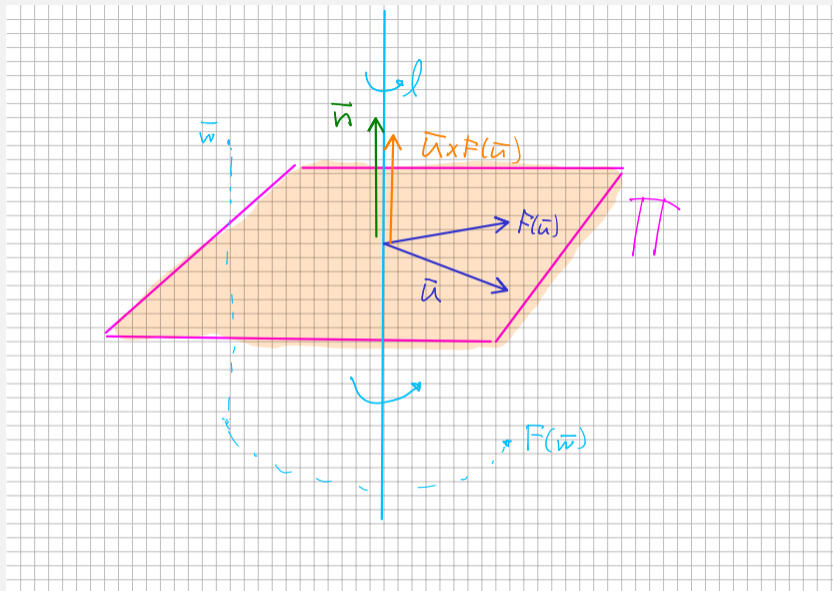
ON-matriser

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Ex För varje $\mu \in \sigma \in S_n$

$$\text{Se } F_\sigma: V \rightarrow V$$

$$F_\sigma(\bar{e}_i) = \bar{e}_{\sigma(i)} \quad \text{Iso}$$

Ex

$$A = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

Är i rummet. Vridningsel
Sötguld?

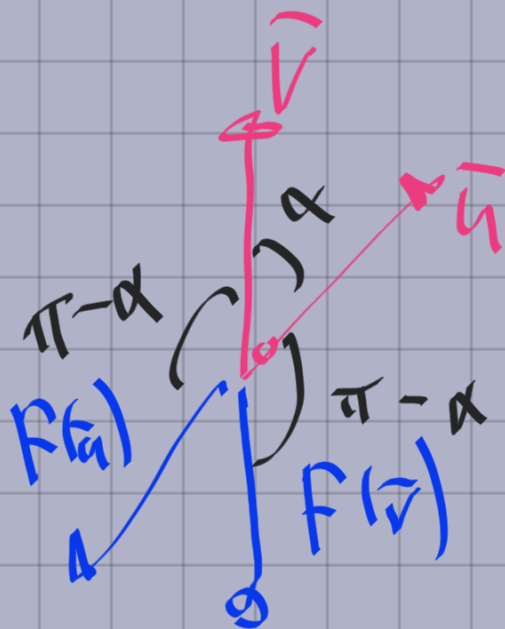
2) Symmetrisk avbildningar.

Def $F: V \rightarrow V$ symm

$$\text{om } (\bar{u} | F(\bar{v})) = (F(\bar{u}) | \bar{v})$$

all \bar{u}, \bar{v} .

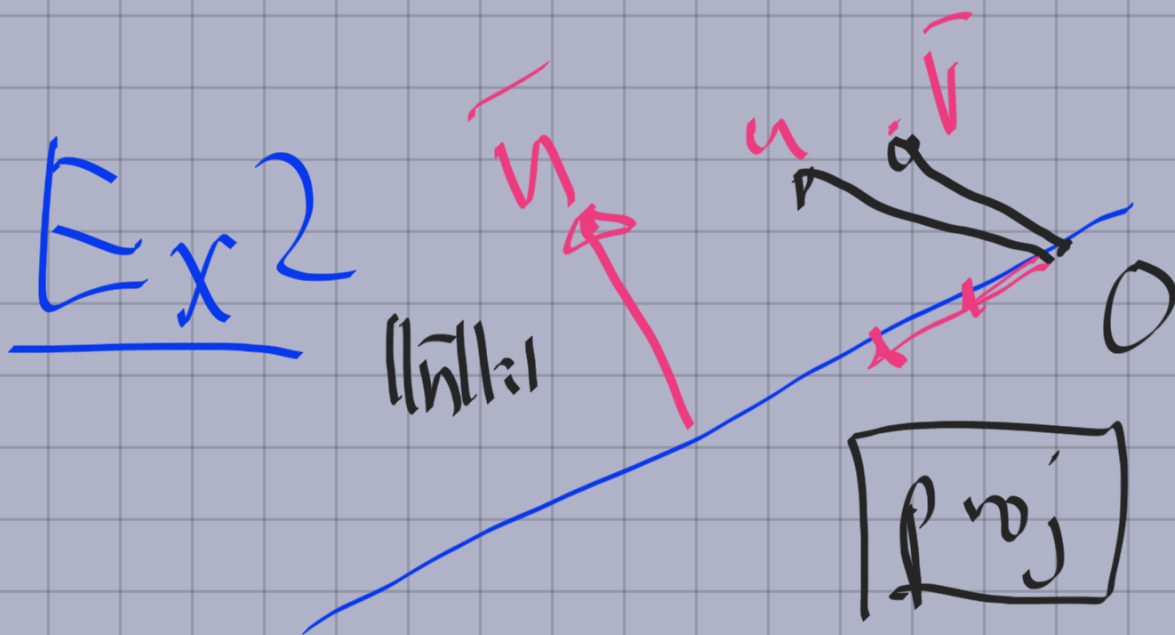
Ex 1



viktig led

$$\begin{aligned} \bar{u} \circ F(\bar{v}) &= \|\bar{u}\| \|F(\bar{v})\| \cdot \cos(\pi - \alpha) \\ &= \|\bar{u}\| \|\bar{v}\| \end{aligned}$$

$$\begin{aligned} \vec{v} \circ \mathbb{P}(\vec{u}) &= \|\vec{v}\| \|\mathbb{P}(\vec{u})\| \cos(\pi - \alpha) \\ &= \|\vec{v}\| \|\vec{u}\| \cos(\pi - \alpha) \end{aligned}$$



$$\mathbb{P}(\vec{u}) = (\vec{u} \circ \vec{n}) \vec{n}$$

$$\mathbb{P}(\vec{v}) = (\vec{v} \circ \vec{n}) \vec{n}$$

$$\begin{aligned} \vec{u} \circ \mathbb{P}(\vec{v}) &= \vec{u} \circ (\vec{v} \circ \vec{n}) \vec{n} \\ &= (\vec{u} \circ \vec{n}) (\vec{v} \circ \vec{n}) \end{aligned}$$

$$\begin{aligned} \mathbb{P}(\vec{u}) \circ \vec{v} &= (\vec{u} \circ \vec{n}) \vec{n} \circ \vec{v} \\ &= (\vec{u} \circ \vec{n}) (\vec{n} \circ \vec{v}) \end{aligned}$$

Satz Om $F(x) = Ax$

Si F sym $\Leftrightarrow A^t = A$.

$$B) (F(\bar{u}) | \bar{v})$$

$$= (F(\underline{x}) | \underline{y})$$

$$= (\underline{Ax} | \underline{y})$$

$$= (Ax)^t y = x^t A^t y$$

\tilde{A} and s, s'

$$\begin{aligned} (\bar{u} \mid F(\bar{v})) &= (\underline{e}X \mid \underline{e}AY) \\ &= X^t AY \end{aligned}$$

$$\text{Si } X^t A^t Y = X^t AY$$

all X, Y

$$\text{Si } A^t = A.$$

Ex Diagonalwert (Skalar)
er stetig, und
100°

$$\begin{pmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -5 \end{pmatrix}$$

symm

Satz (hevis kenne serend)

Om $F: V \rightarrow V$ sym

si finns ON-bas \underline{f}

$$\text{s.} \quad F(\underline{f}) = \underline{f} D F$$

) diagonalmat.

$$\underline{\text{Ex}} \quad A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \quad \text{symm!}$$

$$F(\underline{e}_X) = \underline{e} AX \quad \text{ist vcd?}$$

$$A^2 = \begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix} = 2A$$

$$\text{Sitt} \quad M = \frac{1}{2} A$$

$$M^2 = \frac{1}{4} A^2 = \frac{1}{4} \cdot 2A = \frac{1}{2} A = M$$

$$M = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

$$MX = 0 \Leftrightarrow X = t \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

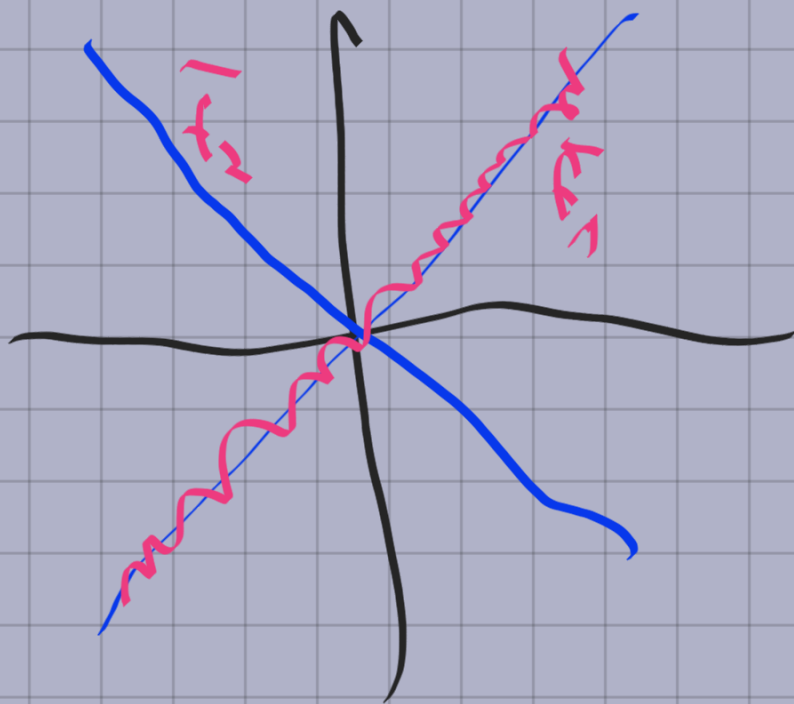
$$MX = X$$

$$\Leftrightarrow MX - X = 0$$

$$(M - I)X = 0$$

$$\left(\begin{array}{cc|c} -1/2 & 1/2 & 0 \\ 1/2 & -1/2 & 0 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

$$A = e \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$



$$G(\vec{F}_1) = \vec{F}_1$$
$$G(\vec{F}_2) = 0$$

Ort \vec{p}_j
pe $[\vec{F}_1]$

A: Ort \vec{p}_j ni $[\vec{F}_1]$ bişit

an einem Strang

mit $k=2$.

