

Ex 1:

a) $A = \begin{pmatrix} 1 & 1 \\ \gamma_1 & \gamma_2 \\ \vdots & \vdots \\ 1 & 1 \end{pmatrix}$ där $\underline{\gamma}_i = F(\bar{u}_i)$ se

$$\underline{A} = \begin{pmatrix} 1 & 2 \\ 3 & 1 \end{pmatrix}$$

b) Alt 1: $F\left(\underline{u} \begin{pmatrix} -1 \\ 2 \end{pmatrix}\right) = F(-\bar{u}_1 + 2\bar{u}_2) =$

$$= -F(\bar{u}_1) + 2F(\bar{u}_2) = -\underline{\gamma} \begin{pmatrix} 1 \\ 3 \end{pmatrix} + 2\underline{\gamma} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \underline{\gamma} \begin{pmatrix} 3 \\ -1 \end{pmatrix}$$

Alt 2: $F(\underline{u} X) = \underline{\gamma} AX$ ger

$$F\left(\underline{u} \begin{pmatrix} -1 \\ 2 \end{pmatrix}\right) = \underline{\gamma} \begin{pmatrix} 1 & 2 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \underline{\gamma} \begin{pmatrix} 3 \\ -1 \end{pmatrix}$$

Ex 2:

Alt 1: $F(x_1, x_2, x_3) = F\left(\underline{e}_2 \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}\right) = (x_1 - 2x_2 + 4x_3, x_2 + 3x_3) = \underline{e}_2 \begin{pmatrix} x_1 - 2x_2 + 4x_3 \\ x_2 + 3x_3 \end{pmatrix} =$

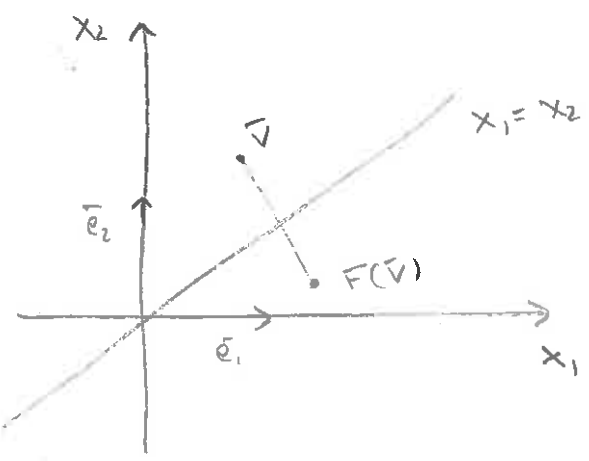
$$= \underline{e}_2 \begin{pmatrix} 1 & -2 & 4 \\ 0 & 1 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

SVAR: $A = \begin{pmatrix} 1 & -2 & 4 \\ 0 & 1 & 3 \end{pmatrix}$

Alt 2: $F(1, 0, 0) = (1, 0) = \underline{e}_2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \underline{e}_2 \gamma_1$, $F(0, 1, 0) = \underline{e}_2 \begin{pmatrix} -2 \\ 1 \end{pmatrix} = \underline{e}_2 \gamma_2$

$$F(0, 0, 1) = \underline{e}_2 \begin{pmatrix} 4 \\ 3 \end{pmatrix} = \underline{e}_2 \gamma_3 ; \quad A = \begin{pmatrix} 1 & 1 & 1 \\ \gamma_1 & \gamma_2 & \gamma_3 \end{pmatrix} = \underline{A}$$

Ex3: $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ spegling genom linjen $x_1 = x_2$. (standardbasen)



Vi noterar att

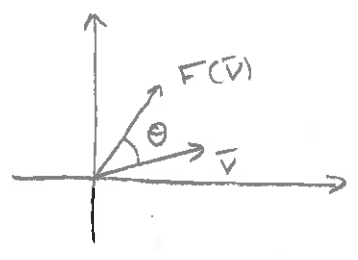
$$F(\bar{e}_1) = \bar{e}_2 = e \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$F(\bar{e}_2) = \bar{e}_1 = e \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

så $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ är F 's matris i standardbasen

Vi får alltså $F(x_1, x_2) = F(e \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}) = e \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = e \begin{pmatrix} x_2 \\ x_1 \end{pmatrix} = (x_2, x_1)$

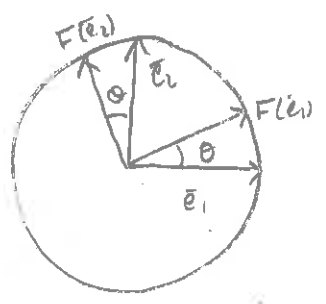
Ex4: Rotation i \mathbb{R}^2 .



$F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ sådan att varje vektor v vrids med en fix vinkel θ .

$$F(\bar{e}_1) = (\cos\theta, \sin\theta)$$

$$F(\bar{e}_2) = (-\sin\theta, \cos\theta)$$



Så $A = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$

($\det A = \cos^2\theta + \sin^2\theta = 1$).

Ex 5: Vridning kring x_3 -axeln i \mathbb{R}^3 .

$$F(\vec{e}_1) = \underline{e} \begin{pmatrix} \cos \theta \\ \sin \theta \\ 0 \end{pmatrix}, \quad F(\vec{e}_2) = \underline{e} \begin{pmatrix} -\sin \theta \\ \cos \theta \\ 0 \end{pmatrix}, \quad F(\vec{e}_3) = \underline{e} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Så $A = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$ ($\det A = 1$).

Ex 6: Alt 1: $F(c_0 + c_1 x + c_2 x^2 + c_3 x^3) = F(\underline{P} \begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{pmatrix}) =$

$$= 2c_0 + 3(c_1 + c_2)x - c_3 x^2 + c_2 x^3 =$$

$$= \underline{P} \begin{pmatrix} 2c_0 \\ 3(c_1 + c_2) \\ -c_3 \\ c_2 \end{pmatrix} = \underline{P} \underbrace{\begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 3 & 3 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{pmatrix}}_A \begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{pmatrix}$$

Alt 2: $F(1) = 2 = \underline{P} \begin{pmatrix} 2 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \quad F(x) = 3x = \underline{P} \begin{pmatrix} 0 \\ 3 \\ 0 \\ 0 \end{pmatrix}$

$$F(x^2) = 3x + x^3 = \underline{P} \begin{pmatrix} 0 \\ 3 \\ 0 \\ 1 \end{pmatrix}, \quad F(x^3) = -x^2 = \underline{P} \begin{pmatrix} 0 \\ 0 \\ -1 \\ 0 \end{pmatrix}$$

$$A = \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 3 & 3 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

Ex 7: π är plan med normalvektor

$\vec{n} = (1, -2, 4)$ genom origo.

Vi tar först fram en formel för $\vec{v}_{\parallel \vec{n}}$:

$$(\vec{x}_1, \vec{x}_2, \vec{x}_3)_{\parallel \vec{n}} = \frac{(\vec{x}_1, \vec{x}_2, \vec{x}_3) \cdot (1, -2, 4)}{|(1, -2, 4)|^2} (1, -2, 4) =$$

$$= \frac{x_1 - 2x_2 + 4x_3}{21} (1, -2, 4)$$

$$F(\vec{v}) = \vec{v} - \vec{v}_{\parallel \vec{n}} \quad \text{så}$$

$$F(x_1, x_2, x_3) = (x_1, x_2, x_3) - \frac{x_1 - 2x_2 + 4x_3}{21} (1, -2, 4) =$$

$$= \frac{1}{21} ((21x_1, 21x_2, 21x_3) - (x_1 - 2x_2 + 4x_3, -2x_1 + 4x_2 - 8x_3, 4x_1 - 8x_2 + 16x_3)) =$$

$$= \frac{1}{21} (20x_1 + 2x_2 - 4x_3, 2x_1 + 17x_2 + 8x_3, -4x_1 + 8x_2 + 5x_3)$$

$$= \frac{1}{21} \begin{pmatrix} 20x_1 + 2x_2 - 4x_3 \\ 2x_1 + 17x_2 + 8x_3 \\ -4x_1 + 8x_2 + 5x_3 \end{pmatrix} = \underline{\underline{\frac{1}{21} \begin{pmatrix} 20 & 2 & -4 \\ 2 & 17 & 8 \\ -4 & 8 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}}}$$

Matris till F .

$$\left(\begin{array}{l} \text{Test: } F(1, -2, 4) = (0, 0, 0) \quad \text{o.k.} \\ F(2, 1, 0) = (2, 1, 0) \quad \text{o.k.} \\ F(4, 0, -1) = (4, 0, -1) \quad \text{o.k.} \end{array} \right)$$

$$G(\bar{V}) = \bar{V} - 2\bar{V}_{11\bar{n}}, \text{ sä p.s.s för } \bar{n}$$

$$G(x_1, x_2, x_3) =$$

$$= \frac{1}{21} ((21x_1, 21x_2, 21x_3) - (2x_1 - 4x_2 + 8x_3, -4x_1 + 8x_2 - 16x_3, 8x_1 - 16x_2 + 32x_3)) =$$

$$= \frac{1}{21} \underline{e} \begin{pmatrix} 19x_1 + 4x_2 - 8x_3 \\ 4x_1 + 13x_2 + 16x_3 \\ -8x_1 + 16x_2 - 11x_3 \end{pmatrix} = \underline{e} \frac{1}{21} \begin{pmatrix} 19 & 4 & -8 \\ 4 & 13 & 16 \\ -8 & 16 & -11 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$\left(\begin{array}{l} \text{Test: } F(1, -2, 4) = (-1, 2, -4) \quad \text{o.k.} \\ F(2, 1, 0) = (2, 1, 0) \quad \text{o.k.} \\ F(4, 0, -1) = (4, 0, -1) \quad \text{o.k.} \end{array} \right)$$