

**Written examination, TATM38 Mathematical Models in Biology**

**2025-01-09 , 14.00 - 19.00**

Each problem is worth 4 points. To obtain a grade 3, 4 or 5, you need 10, 14 or 18 points, respectively. You must not use any aids (no textbooks, notes, calculators or other electronic tools).

- 1.** (a) The interaction between two species  $x(t)$  and  $y(t)$  is modeled by the linear system

$$\begin{pmatrix} x'(t) \\ y'(t) \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 0.25 & -1 \end{pmatrix} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} .$$

Determine the general solution to this system and draw a picture of the entire phase plane (including negative  $x$  and  $y$ ). Is the steady state (= equilibrium point)  $(0, 0)$  stable?

- (b) Give also the general solution to the system of difference equations

$$\begin{pmatrix} x_{n+1} \\ y_{n+1} \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 0.25 & -1 \end{pmatrix} \begin{pmatrix} x_n \\ y_n \end{pmatrix} .$$

Is  $(0, 0)$  stable in this case?

- 2.** A population  $N_n$  is described by the time discrete model

$$N_{n+1} = \frac{3N_n}{1 + N_n} , \quad n = 0, 1, 2, \dots$$

Find all steady states (= equilibrium points) and determine their stability. What happens to the population as  $n \rightarrow \infty$  if  $N_0 > 0$ ? Sketch a cobweb diagram.

- 3.** An ecosystem model for phytoplankton  $P(t)$ , zooplankton  $Z(t)$ , and nitrogen leads to the two-dimensional dynamical system for  $P(t)$  and  $Z(t)$ :

$$\begin{cases} \frac{dP}{dt} = P(2 - 2P - Z) \\ \frac{dZ}{dt} = Z(2P - 1) \end{cases}$$

Find all steady states of the system and determine their stability. Draw, for  $P \geq 0$  and  $Z \geq 0$ , a phase plane picture with nullclines and directions of the vector field. What happens to the populations as  $t \rightarrow \infty$  if  $P(0) > 0$  and  $Z(0) > 0$ ?

**PLEASE TURN**

4. A model for two populations  $x(t)$  and  $y(t)$  is given by

$$\begin{cases} \frac{dx}{dt} = 2x \left(1 - \frac{2x}{1+y}\right) \\ \frac{dy}{dt} = y \left(1 - \frac{y}{2+x}\right) \end{cases}$$

Find all steady states and determine their stability. Draw a phase plane picture (with nullclines and directions of the vector field).

What happens to the populations as  $t \rightarrow \infty$  if a)  $x(0) = 0$  and  $y(0) > 0$ , b)  $x(0) > 0$  and  $y(0) = 0$ , c)  $x(0) > 0$  and  $y(0) > 0$ ?

Explain why this a mutualist population model. (Mutualist means that both populations benefit from the presence of the other population.)

5. For  $0 < x < 2$  and  $t > 0$ , solve the initial-boundary value problem (IBVP) for  $u(t, x)$

$$\begin{cases} 2u_t = u_{xx} - 2u \\ u_x(t, 0) = 0 \\ u_x(t, 2) = 0 \\ u(0, x) = 3 + 4 \cos \pi x \end{cases}$$

Hint: put  $u(t, x) = v(t, x)e^{\alpha t}$ .

6. Consider a reactor-diffusion system in one space dimension for the functions  $u(t, x)$  and  $v(t, x)$

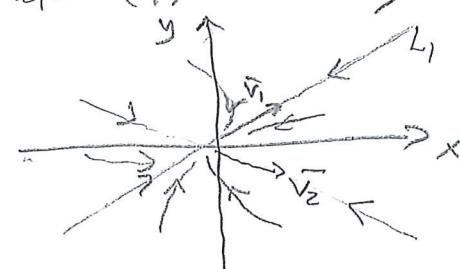
$$\begin{cases} u_t = R_1(u, v) + D_1 u_{xx} \\ v_t = R_2(u, v) + D_2 v_{xx} \end{cases}$$

In a spatially uniform steady state  $(\bar{u}, \bar{v})$  (this means  $R_1(\bar{u}, \bar{v}) = R_2(\bar{u}, \bar{v}) = 0$ ), for which of the following three Jacobi matrices  $J(\bar{u}, \bar{v})$  can we have Turing diffusive instabilities?

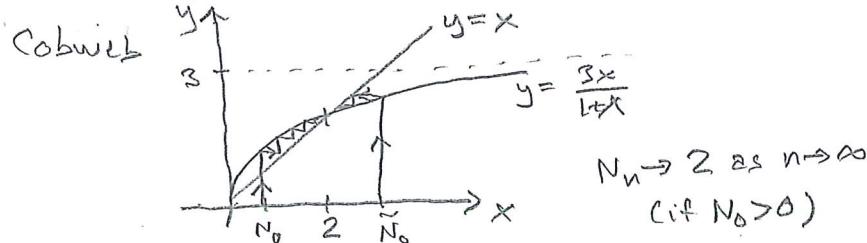
$$J_1 = \begin{pmatrix} -1 & 3 \\ -1 & -1 \end{pmatrix} \quad J_2 = \begin{pmatrix} -1 & 3 \\ -1 & 2 \end{pmatrix} \quad J_3 = \begin{pmatrix} -2 & 3 \\ -1 & 1 \end{pmatrix}$$

Justify your answer clearly.

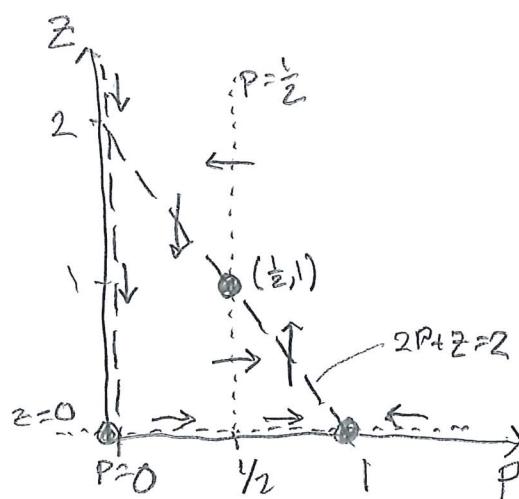
For the matrix that allows diffusive instability, assume now that  $0 < x < 6\pi$ ,  $D_1 = 9$  and  $D_2 = 1$ . Find the values of  $n$  for which unstable (pattern forming) modes  $e^{\sigma t} \cos \frac{nx}{6}$  ( $\sigma > 0$ ) appear, and sketch the resulting one-dimensional patterns.

- ① a)  $\begin{pmatrix} x' \\ y' \end{pmatrix} = \underbrace{\begin{pmatrix} -1 & 1 \\ 0.25 & -1 \end{pmatrix}}_A \begin{pmatrix} x \\ y \end{pmatrix}$ , Eigenvalues  $\begin{vmatrix} -1-\lambda & 1 \\ 0.25 & -1-\lambda \end{vmatrix} = \lambda^2 + 2\lambda + 0.75 = 0$   
 $\Rightarrow \lambda_1 = -\frac{1}{2}, \lambda_2 = -\frac{3}{2}$ , Eigenvectors  $\lambda_1 = -\frac{1}{2} \Rightarrow \vec{v}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \lambda_2 = -\frac{3}{2} \Rightarrow \vec{v}_2 = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$   
General solution is  $\begin{pmatrix} x \\ y \end{pmatrix} = k_1 e^{2t/2} \vec{v}_1 + k_2 e^{-3t/2} \vec{v}_2 = k_1 e^{-t/2} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + k_2 e^{-3t/2} \begin{pmatrix} 2 \\ -1 \end{pmatrix}$   
*i.e.,  $k_1, k_2$  constants*
- phase plane:
- 
- (0,0) is stable since both  $\lambda_1 < 0$  and  $\lambda_2 < 0$
- (solutions approach (0,0) along  $L_1$  as  $t \rightarrow \infty$ )
- (0,0) is unstable since  $|\lambda_2| = \frac{3}{2} > 1$

- ②  $\bar{N}$  steady state of  $N_{n+1} = \frac{3N_n}{1+N_n}$  if  $\bar{N} = \frac{3\bar{N}}{1+\bar{N}} \Rightarrow \bar{N}_1 = 0 \text{ or } \bar{N}_2 = 2$   
Stability  $f(N) = \frac{3N}{1+N} \Rightarrow f'(N) = \frac{3}{(1+N)^2} \Rightarrow |f'(0)| = 3 > 1 \text{ and } |f'(2)| = \frac{1}{3} < 1$   
 $\Rightarrow \begin{cases} \bar{N}_1 = 0 \text{ unstable} \\ \bar{N}_2 = 2 \text{ stable} \end{cases}$



- ③  $\begin{cases} P' = P(2-2P-Z) \\ Z' = Z(2P-1) \end{cases}$  P nullclines:  $P=0, 2P+Z=2$  ---  
Z nullclines:  $Z=0, P=1/2$  .....



3 steady states:  $(\bar{P}_1, \bar{Z}_1) = (0, 0), (\bar{P}_2, \bar{Z}_2) = (1, 0)$   
 $(\bar{P}_3, \bar{Z}_3) = (\frac{1}{2}, 1)$

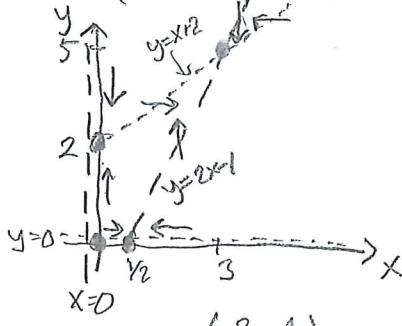
 $J(P, Z) = \begin{pmatrix} 2-4P-Z & -P \\ 2Z & 2P-1 \end{pmatrix} \Rightarrow J(0, 0) = \begin{pmatrix} 2 & 0 \\ 0 & -1 \end{pmatrix} \left\{ \begin{array}{l} \lambda_1 = 2 > 0 \\ \lambda_2 = -1 < 0 \end{array} \right\} \Rightarrow \text{saddle, unstable}$ 
 $J(1, 0) = \begin{pmatrix} -2 & -1 \\ 0 & 1 \end{pmatrix} \left\{ \begin{array}{l} \lambda_1 = -2 < 0 \\ \lambda_2 = 1 > 0 \end{array} \right\} \Rightarrow \text{saddle, unstable}$ 
 $J(\frac{1}{2}, 1) = \begin{pmatrix} -1 & -1/2 \\ 2 & 0 \end{pmatrix} = \boxed{\det J = 1 > 0} \Rightarrow \text{stable}$ 

[or  $\det(J-\lambda I) = \lambda^2 + \lambda + 1 = 0 \Rightarrow \lambda_{1,2} = -\frac{1}{2} \pm \frac{i\sqrt{3}}{2} \Rightarrow$   
 $\operatorname{Re}(\lambda_{1,2}) = -\frac{1}{2} < 0 \Rightarrow \text{stable (spiral)}$ ]

$(P(t), Z(t)) \rightarrow (\frac{1}{2}, 1) \text{ as } t \rightarrow \infty \text{ if } P(0) > 0 \text{ and } Z(0) > 0$

Populations can coexist.

(4)  $\begin{cases} x' = 2x(1 - \frac{2x}{1+y}) \\ y' = y(1 - \frac{y}{2+x}) \end{cases}$  x nullclines  $x=0, 2x=1+y \Rightarrow y=2x-1$   
 y nullclines  $y=0, y=2+x$



4 steady states  $(0,0), (\frac{1}{2},0), (0,2)$  and  $(3,5)$  ( $y=2+x=2x-1 \Rightarrow x=3 \Rightarrow y=5$ )  
 $J(x,y) = \begin{pmatrix} 2 - \frac{8x}{1+y} & \frac{4x^2}{(1+y)^2} \\ \frac{y^2}{(2+x)^2} & 1 - \frac{2y}{2+x} \end{pmatrix} \Rightarrow J(0,0) = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}, \begin{cases} \lambda_1 = 2 > 0 \\ \lambda_2 = 1 > 0 \end{cases} \Rightarrow \text{unstable}$   
 $J(\frac{1}{2},0) = \begin{pmatrix} -2 & 1 \\ 0 & 1 \end{pmatrix}, \begin{cases} \lambda_1 = -2 < 0 \\ \lambda_2 = 1 > 0 \end{cases} \Rightarrow \text{unstable (saddle)}, J(0,2) = \begin{pmatrix} 2 & 0 \\ 1 & -1 \end{pmatrix}, \begin{cases} \lambda_1 = 2 > 0 \\ \lambda_2 = -1 < 0 \end{cases} \Rightarrow \text{unstable (saddle)}$   
 $J(3,5) = \begin{pmatrix} -2 & 1 \\ 1 & -1 \end{pmatrix}, \lambda_{1,2} = -\frac{3}{2} \pm \frac{\sqrt{5}}{2} < 0 \Rightarrow \text{stable}$  (or  $\det J = 1 > 0, \text{Tr } J = -3 < 0 \Rightarrow \text{stable}$ )

a)  $x(0)=0, y(0)>0 \Rightarrow (x(t), y(t)) \rightarrow (0,2)$  as  $t \rightarrow \infty$  (along y-axis)

b)  $x(0)>0, y(0)=0 \Rightarrow (x(t), y(t)) \rightarrow (\frac{1}{2},0)$  as  $t \rightarrow \infty$  (along x-axis)

c)  $x(0)>0, y(0)>0 \Rightarrow (x(t), y(t)) \rightarrow (3,5)$  as  $t \rightarrow \infty$ , larger asymptotic values for both populations if both present (so mutualist) ( $3 > \frac{1}{2}, 5 > 2$ )

(5)  $u(t,x) = v(t,x)e^{xt} \Rightarrow u_t = (v_t + \alpha v)e^{xt}, u_x = v_x e^{xt}, u_{xx} = v_{xx} e^{xt} \Rightarrow$   
 $2u_t = u_{xx} - 2u \Leftrightarrow 2(v_t + \alpha v)e^{xt} = (v_{xx} - 2v)e^{xt}$ . choose  $\alpha = -1$  to get  $2v_t = v_{xx}$   
 and the IVP for  $v(t,x)$ :

$$\begin{cases} 2v_t = v_{xx} \\ v_x(t,0) = u_x(t,0)e^{0t} = 0 \\ v_x(t,2) = u_x(t,2)e^{0t} = 0 \\ v(0,x) = u(0,x)e^0 = 3 + 4\cos\pi x \end{cases}$$

Separation of variables  $v(t,x) = T(t)\Xi(x) \Rightarrow$   
 $\frac{2T'(t)}{T(t)} = \frac{\Xi''(x)}{\Xi(x)} = \lambda = \text{constant} \Rightarrow T(t) = e^{\lambda t/2}$   
 $\begin{cases} v_x(t,0) = T(t)\Xi'(0) = 0 \\ v_x(t,2) = T(t)\Xi'(2) = 0 \end{cases} \Rightarrow \Xi'(0) = \Xi'(2) = 0$   
 $\Xi''(x) - \lambda \Xi(x) = 0$   
 $\Xi'(0) = \Xi'(2) = 0 \Rightarrow \Xi_n(x) = \cos \frac{n\pi x}{2}, n=0,1,2,\dots$  (non-zero solutions),  $\lambda = -\frac{n^2\pi^2}{4}$   
 $\Rightarrow T_n(t) = e^{-n^2\pi^2 t/8}$

Linear PDE and homog. boundary conditions  $\Rightarrow$

$$v(t,x) = \sum_{n=0}^{\infty} \alpha_n e^{-n^2\pi^2 t/8} \cos \frac{n\pi x}{2}, \text{ Initial condition } v(0,x) = 3 + 4\cos\pi x \Rightarrow$$

$$\sum_{n=0}^{\infty} \alpha_n \cos \frac{n\pi x}{2} = 3 + 4\cos\pi x, \text{ identify } \alpha_0 = 3, \alpha_2 = 4, \alpha_n = 0 \text{ for } n \neq 0,2 \Rightarrow$$

$$v(t,x) = 3 + 4e^{-\pi^2 t/2} \cos\pi x \Rightarrow u(t,x) = 3e^{-t} + 4e^{-(\frac{\pi^2}{2})t} \cos\pi x$$

(6) The Turing conditions for diffusive instabilities are

$$J_1 = \begin{pmatrix} -1 & 3 \\ -1 & -1 \end{pmatrix} \text{ has } j_{11} = j_{22} = -1 \Rightarrow 3, \text{ cannot be satisfied}$$

$$J_2 = \begin{pmatrix} -1 & 3 \\ -1 & 2 \end{pmatrix} \text{ has } \text{Tr } J_2 = -1+2=1 > 0 \Rightarrow 1, \text{ not satisfied}$$

$J_3 = \begin{pmatrix} -2 & 3 \\ -1 & 1 \end{pmatrix}$  has  $\text{Tr } J_3 = -1 < 0$  (1. satisfied),  $\det J_3 = 1$  (2. satisfied) and 3. is  $-2D_2 + D_1 > 2\sqrt{D_1 D_2}$  which can be satisfied (depending on  $D_1$  and  $D_2$ ). With  $D_1 = 9$  and  $D_2 = 1$ ,  $-2D_2 + D_1 = -2 + 9 = 7 > 6 = 2\sqrt{9 \cdot 1}$  so 3. satisfied.

With  $u = \frac{j_{11}D_2 + j_{22}D_1}{D_1D_2} = \frac{-7}{9}, w = \frac{\det J}{D_1D_2} = \frac{1}{9}, \Delta = \sqrt{\frac{u^2}{4} - w} = \frac{\sqrt{13}}{18}$ , unstable perturbations

appear for  $\frac{u}{2} - \Delta < q^2 = \frac{n^2}{36} < \frac{u}{2} + \Delta \Leftrightarrow 14 - 2\sqrt{13} < n^2 < 14 + 2\sqrt{13}$  ( $3 < \sqrt{13} < 4 \Rightarrow 6 < 14 - 2\sqrt{13} < 8$   
 $20 < 14 + 2\sqrt{13} < 22$ )

$\Rightarrow n=3 \text{ or } n=4$  :

